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U N I V E R S I T Y   O F   B E R G E N

Department of Physics and Technology

# Studying two Higgs doublet models using machine learning

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## Theoretical motivation

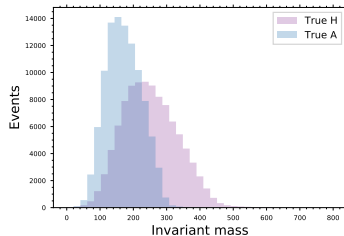
- In the Standard Model, we have an SU(2) doublet  $\phi$  corresponding to one physical particle, the Higgs boson ( $h$ , 125 GeV)

$$\mathcal{L} = -\frac{1}{4}F_{\mu\nu}F^{\mu\nu} + i\bar{\psi}\not{D}\psi + \psi_i y_{ij} \psi_j \phi + |D_\mu \phi|^2 - V(\phi) \quad (1)$$

- A minimal extension of the Higgs sector is to add one more doublet - i.e. a *two Higgs doublet model* (2HDM)
- This addition results in a total of five physical states:
  - One light scalar  $h$ , this one we know
  - Two charged ones, which are easily separable
  - Two neutral ones,  $A$  and  $H$ , which have opposite charge under  $CP$ , but can be degenerate in mass

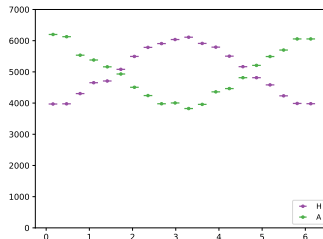
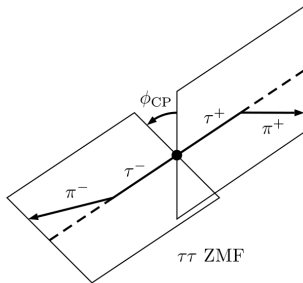
# Main idea

- Typical searches (ATLAS [1], CMS [2]) look for *any* particle decaying to ditau, but don't attempt to distinguish them [1] CERN-EP-2016-164, [2] CMS PAS HIG-13-021
  - ... mainly because it's difficult. No direct access to the  $CP$  numbers
  - Miss out on vital information this way
- We propose to:
  - Use machine learning to separate  $A$  and  $H$
  - From the classified events, deduce model parameters in two different cases:
    - *Both  $A$  and  $H$  have the same mass*: Measure cross section times branching ratio for the two, separately
    - *$A$  and  $H$  have unequal, but similar mass*: Measure the mass difference



# Inputs

- Look at the decay  $A/H \rightarrow \tau\tau \rightarrow \pi^+\pi^0\nu\pi^-\pi^0\nu$
- Fundamental info: 4-momenta of 4 particles, plus missing transverse energy
- Derived info: various angles, energy ratios, impact parameters
  - One angle of particular importance: Angle between decay planes

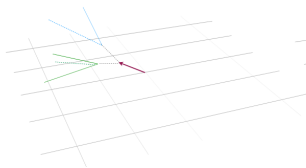


- Generating all datasets using Pythia8.2

# Processing inputs

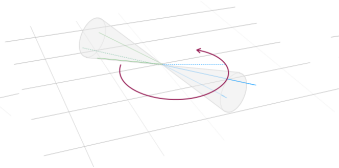
- Need to choose a standard frame of reference
- When doing so, the 16 4-vector components are reduced to 11 independent variables

1: Boost to visible rest frame



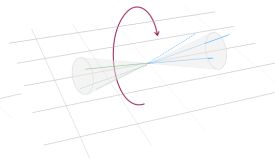
$\tau^-$	$p_x$	$p_y$	$p_z$	$E$
$\tau^+$	$p_x$	$p_y$	$p_z$	$E$
$\pi^-$	$p_x$	$p_y$	$p_z$	$E$
$\pi^0(-)$	$p_x$	$p_y$	$p_z$	$E$
$\pi^+$	$p_x$	$p_y$	$p_z$	$E$
$\pi^0(+)$	$p_x$	$p_y$	$p_z$	$E$

2: Rotate to align with z axis



$\tau^-$	0	0	$p_z$	$E$
$\tau^+$	0	0	$-p_z$	$E$
$\pi^-$	$p_x$	$p_y$	$p_z$	$E$
$\pi^0(-)$	$p_x$	$p_y$	$p_z$	$E$
$\pi^+$	$p_x$	$p_y$	$p_z$	$E$
$\pi^0(+)$	$p_x$	$p_y$	$p_z$	$E$

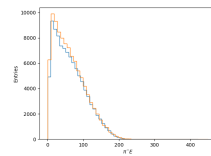
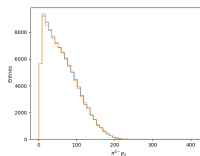
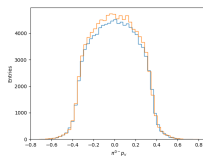
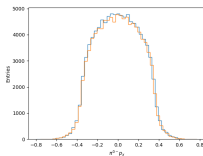
3: Rotate so that  $\pi^-$  has zero x-component



$\tau^-$	0	0	$p_z$	$E$
$\tau^+$	0	0	$-p_z$	$E$
$\pi^-$	0	$p_y$	$p_z$	$E$
$\pi^0(-)$	0	$-p_y$	$p_z$	$E$
$\pi^+$	$p_x$	$p_y$	$p_z$	$E$
$\pi^0(+)$	$-p_x$	$-p_y$	$p_z$	$E$

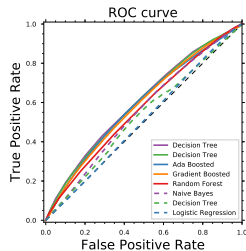
# Neural network

- Implemented a fully-connected feed-forward neural network in Keras (i.e. standard Dense() layers)
- ReLu activation functions, Adam optimiser, batch normalisation included
- so far tested 2-4 hidden layers with  $\sim 300$  nodes each
- Not the easiest problem ever attempted with machine learning
  - Extremely overlapping feature distributions, no single 'killer' feature. Need to rely on correlations
  - Simple-ish network implementation achieves  $\sim 0.61$  ROC AUC



# Summary

- Currently optimising network structure
- Other classifiers tested, no immediate success
- Still thinking through some open issue, related to
  - Feature engineering
  - Feature scaling
  - Uncertainty estimation





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